

## Preliminary inquiry form for Controllable passive anti-rolling tank DELIN

									٦	1	IC.									
Ship type	General Inf																			
Design Design											OWI	CI								
Bureau											Shipy	ard								
Contact	C	Company								II.		Title						Dat	te	
	7	Γel				F	ax					Emai	1							
M:稳心					船舶参数示意						II	P	Please provide as more as possible						Ye	s: √
						m. i.e.		án eir				Gene	eneral arrangement (GA)							
I	水线		+	-	船宽		= ,	±48	Midship section plan											
横锯角	小坂		型深		G		/ +	★线	Hull lines											
G:重心 /	B•						72	*	Calcu	Calculation of balance and stability										
	/ E		KT							Pleas	Please provide the relative data/drawings									
		A.F	)		F,P							if th	the dimension and location of the							
	/ * <sup>#</sup>						k线 ■		anti-r	ti-rolling tank are already planned										
	Lpp Log									Please inform us other items to be										
	- 200								-					nsidered during the design, including						
								the requirement from ship owner.							<u> </u>					
T				1	т	В	Τ		Т	ame	ters draft	(1)			l	I	D	1		
Lpp	nt			m	1	5		t	1	n (	aran	( <b>a</b> )			m		D			m
Displacement Frame	nt –				m	D;1	ga ka		B)			X		m		Ic the	ere stabil	izer		t
spacing(F.S.)			m Bilge keel (L $\times$ B)										fin?	12.01						
				Service navigation zone										Ser	vice speed					knot
The distance between the bo											draw									
of ART and ship baseline																				
Est. launching date					Е						Est. date of vessel delivery									
								I	Loac	ding	Info									
Loading condition				Fully loaded departure						Fully loaded arrival					Regular status					
Displacement [t]																				
Draft [m]																				
Height of Co	OG (	KG) [1	m]																	
GM [m]																				
Unrevised (GoM) [m]																				
СЬ																				
Coeff of waterline (Cw)																				
Max roll angle																				
Rolling peirod [sec]																				
				,			E	xpected	d Aı	nti-ro	olling	g Effect	t							
Sea state					Roll angle before anti-rolling							0	。 Roll ar			ngle after anti-rolling				0
(hw/3)			m		(ca	lculat	ed va	ılue)					(expected value)							